

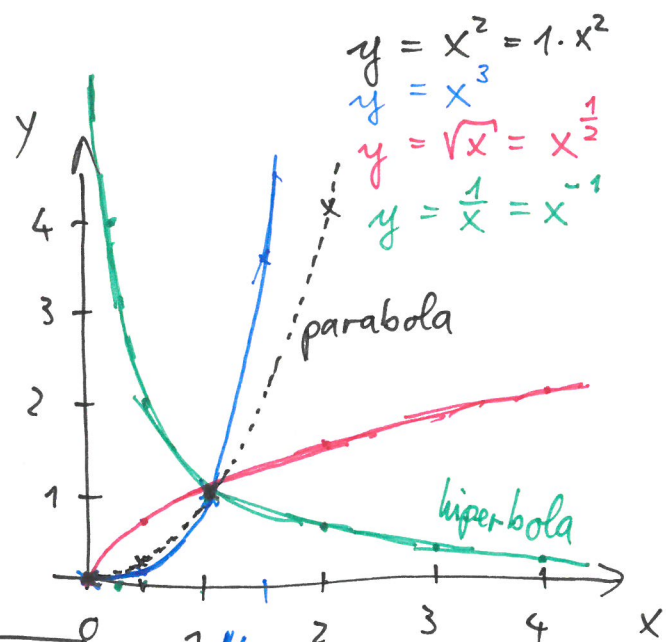
$$A \sim a^2$$

$$(A = 6a^2)$$

$$V \sim a^3$$

$$(V = a^3)$$

$$y = b \cdot x^a$$

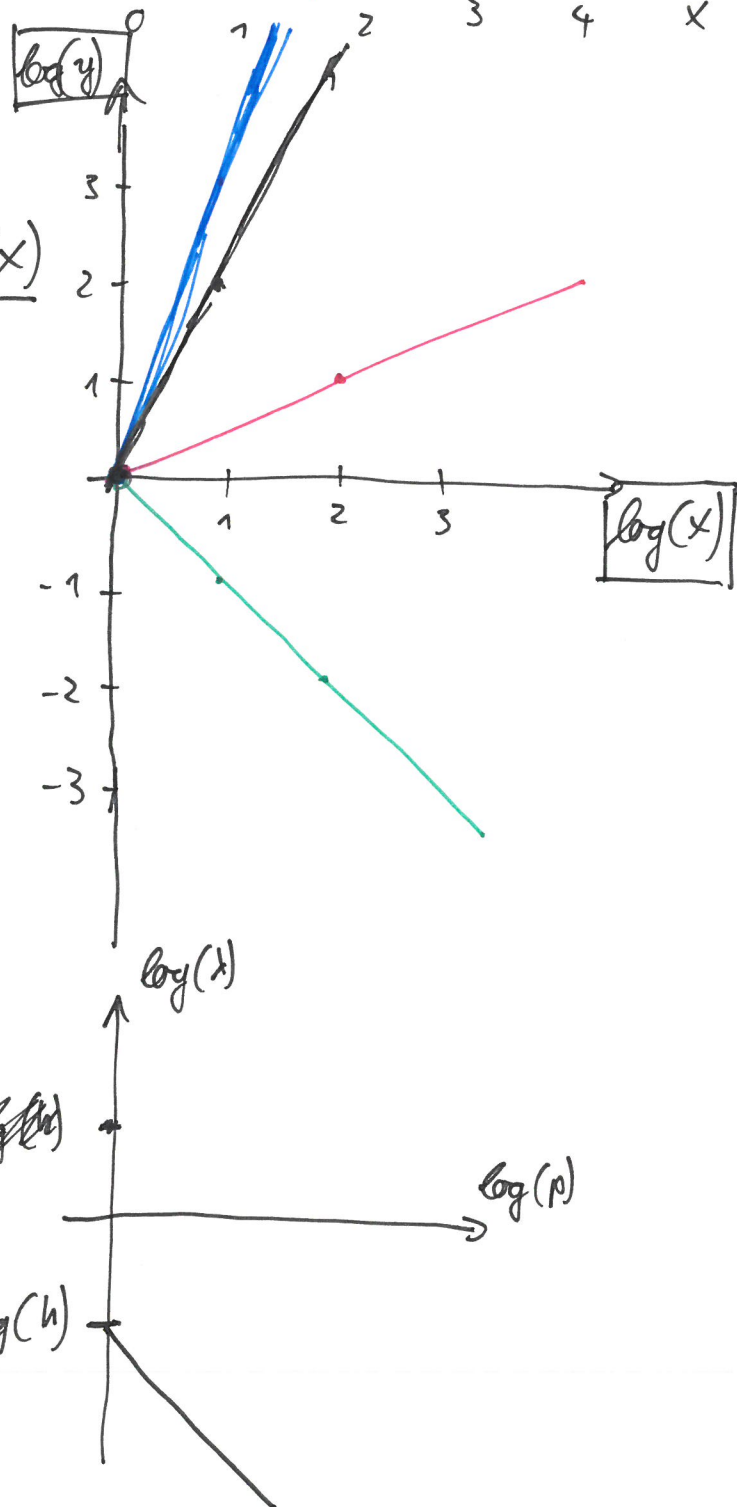


linearizació

$$\begin{aligned} \log(y) &= \log(b \cdot x^a) \\ &= \log(b) + \log(x^a) \end{aligned}$$

$$\log(y) = \log(b) + a \cdot \log(x)$$

$$y = b + a \cdot x$$

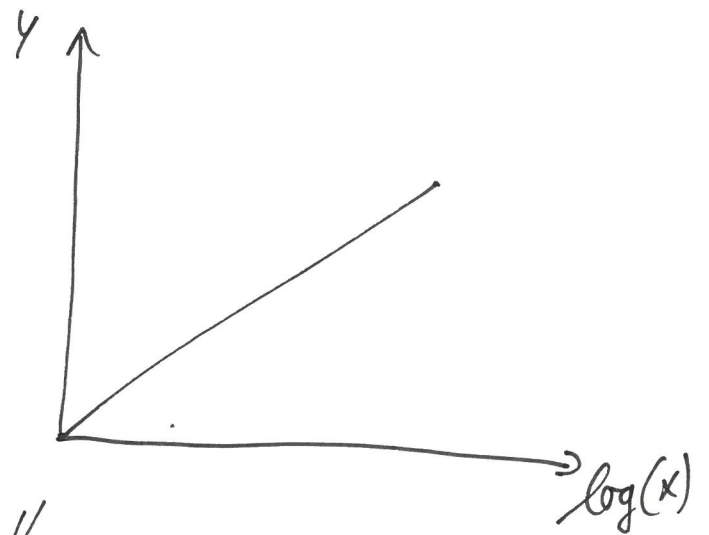
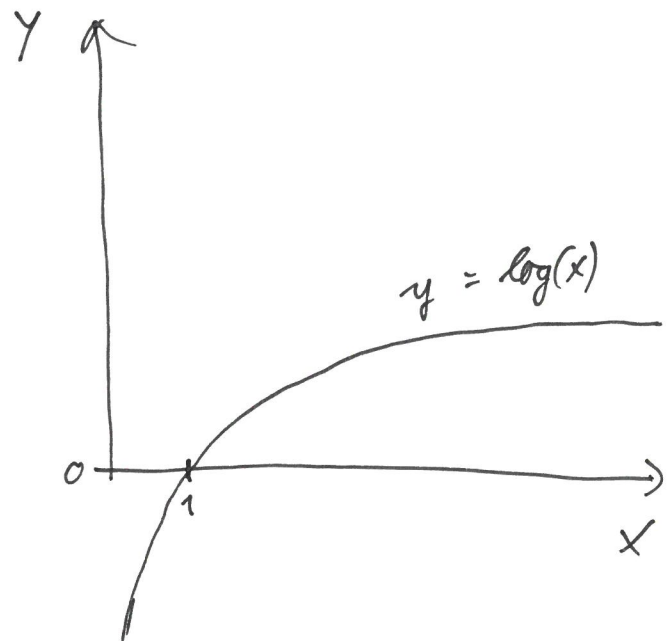


$$\lambda = \frac{h}{p} = h \cdot \frac{1}{p} = h \cdot p^{-1}$$

$$\log(\lambda) = \log(h) + (-1) \cdot \log(p)$$

$$y = b \cdot \log_a(x)$$

linearizálás:



$$\begin{aligned} 1.g) \quad \frac{1}{2} m \cdot v^2 &= \frac{3}{2} k T \\ m \cdot v^2 &= 3 k \cdot T \\ \frac{m \cdot v^2}{3 \cdot k} &= T \end{aligned}$$

$$\begin{aligned} // \cdot 2 \\ // \div (3 k) \end{aligned}$$

$$\begin{aligned} 2.e) \quad \frac{1}{2} m \cdot v^2 &= \frac{3}{2} k T \\ m v^2 &= 3 k T \\ v^2 &= \frac{3 k T}{m} \\ v &= \sqrt{\frac{3 k T}{m}} \end{aligned}$$

$$\begin{aligned} // \cdot 2 \\ // \div m \\ // \sqrt{} \end{aligned}$$

4.a)

$$I = I_0 \cdot e^{-\mu \cdot x} \quad // \div I_0$$

$$\frac{I}{I_0} = e^{-\mu \cdot x} \quad // \ln()$$

$$\ln\left(\frac{I}{I_0}\right) = \ln(e^{-\mu \cdot x}) = -\mu \cdot x \cdot \underbrace{\ln(e)}_1 = -\mu \cdot x \quad // \div (-\mu)$$

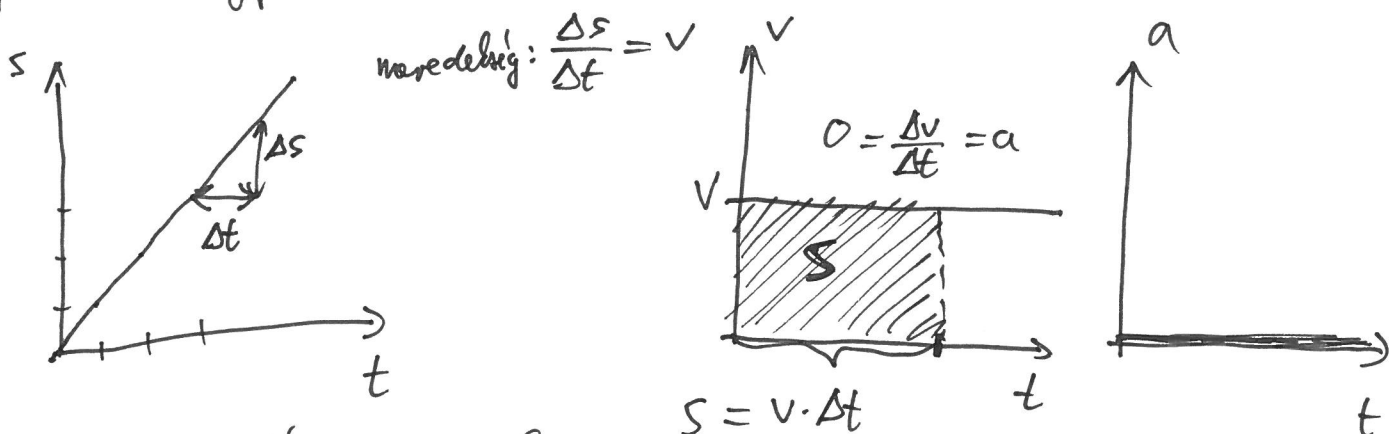
$$\frac{\ln\left(\frac{I}{I_0}\right)}{-\mu} = x$$

$$\ln\left(\frac{I}{I_0}\right) = \ln\left(\left(\frac{I_0}{I}\right)^{-1}\right) = -1 \cdot \ln\left(\frac{I_0}{I}\right)$$

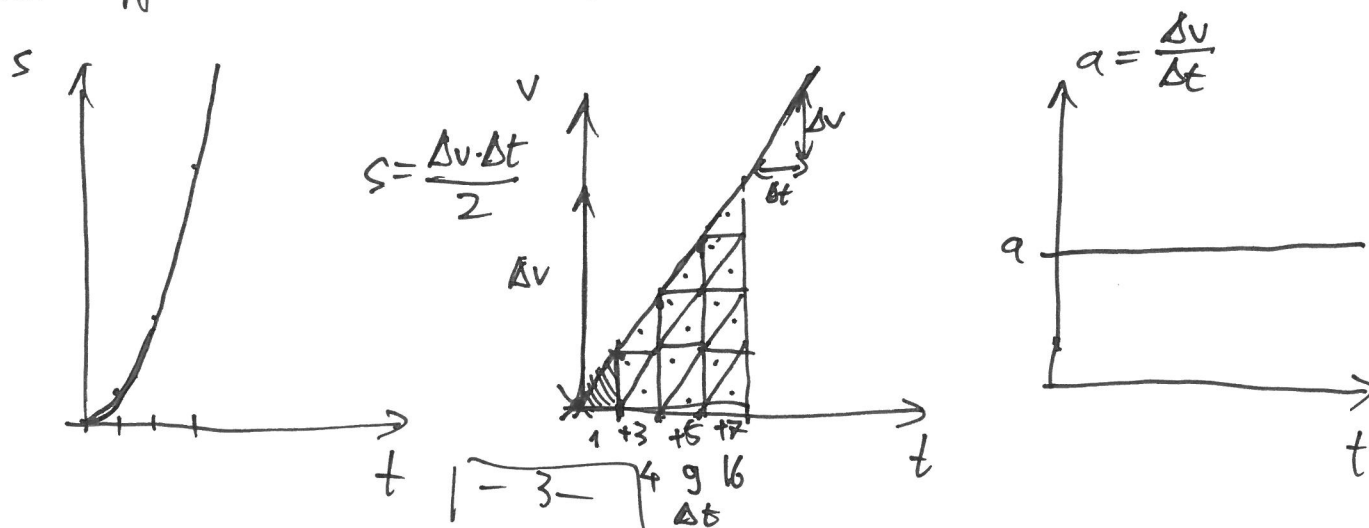
$$\frac{\ln\left(\frac{I_0}{I}\right)}{\mu} = x$$

egyeses vonalú mozgások.

① egyeneses mozgás: $v = \text{konst.}$

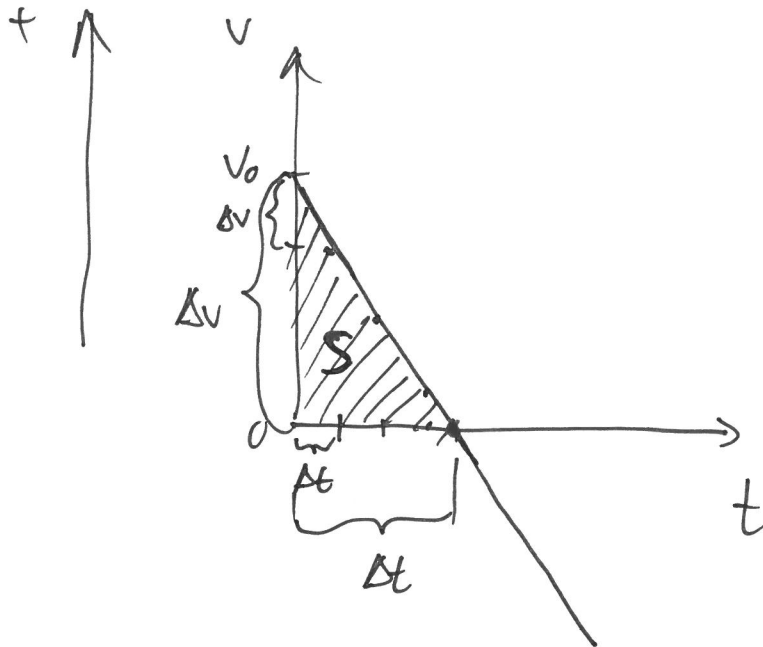


② egyeneses gyorsulás: $a = \text{konst.}$



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$$a = \text{const} < 0$$



$$3/7 \quad v_0 = 36 \frac{\text{km}}{\text{h}} = 36 \frac{1000 \text{ m}}{3600 \text{ s}} = 10 \frac{\text{m}}{\text{s}}$$

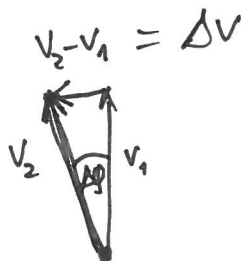
$$a) \quad \left. \begin{array}{l} |\Delta v| = v_0 \\ a = g = \frac{\Delta v}{\Delta t} \end{array} \right\} \Delta t = \frac{\Delta v}{g} = \frac{10 \frac{\text{m}}{\text{s}}}{10 \frac{\text{m}}{\text{s}^2}} \approx 1 \text{ s}$$

$$g \cdot \Delta t = \Delta v$$

$$\Delta t = \frac{\Delta v}{g}$$

$$\frac{\left(\frac{\text{m}}{\text{s}}\right)}{\left(\frac{\text{m}}{\text{s}^2}\right)} = \frac{\text{m}}{\text{s}} \cdot \frac{\text{s}^2}{\text{m}} = \text{s}$$

$$b) \quad s = \frac{\Delta v \cdot \Delta t}{2} = \frac{10 \frac{\text{m}}{\text{s}} \cdot 1 \text{ s}}{2} = 5 \text{ m}$$



$$\frac{\Delta v}{v} = \frac{v \cdot \Delta t}{r}$$

$$\Delta v = \frac{v^2 \cdot \Delta t}{r}$$

$$a_{\text{cp}} = \frac{\Delta v}{\Delta t} = \frac{v^2}{r} \quad \frac{\left(\frac{\text{m}}{\text{s}}\right)^2}{\text{m}} = \frac{\text{m}}{\text{s}^2}$$

3/9

$$r = 8 \text{ m}$$

$$\Delta t = 3,5 \text{ min} = 210 \text{ s}$$

$$N = 20$$

$$a) T = \frac{\Delta t}{N} = \frac{210 \text{ s}}{20} = 10,5 \text{ s}$$

$$b) f = \frac{1}{T} = \frac{1}{10,5 \text{ s}} = \frac{20}{210 \text{ s}} = 0,0952 \frac{1}{\text{s}} = 0,0952 \text{ Hz}$$

$$c) \omega = \frac{\Delta \varphi}{\Delta t} = \frac{2\pi \text{ rad}}{T} = \frac{2\pi \text{ rad}}{10,5 \text{ s}} = 0,598 \frac{\text{rad}}{\text{s}} = 0,598 \frac{1}{\text{s}}$$

$$d) v = \omega \cdot r = 0,598 \frac{1}{\text{s}} \cdot 8 \text{ m} = 4,787 \frac{\text{m}}{\text{s}}$$